

Path Objects

Introduction

A **Path** object manages coordinated multi-axis motion profiles. It is used when the motion profiles in an N-Dimensional space are required to follow a specific coordinated trajectory. Motion paths are constructed with high level linear and arc segments and downloaded to the controller. The controller calculates the real-time individual axis profiles.

Generally, Path motion is used when the trajectory through space is more important than the final target position. Several different algorithms can be applied to convert the linear and arc segment path into an interpolated trajectory.

Path trajectory generation is now supported by PT, PVT, SPLINE, BESSEL, BSPLINE, and BSPLINE2 algorithms. Blending of the corners is only available for the 2 bspline algorithms. Blending of a corner is when the path does not hit the corner but goes through a smooth arc.

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mpiPathCreate

Declaration

```
MPIPath mpiPathCreate( );
```

Required Header: stdmpi.h

Description

mpiPathCreate creates a Path object.

Return Values

handle	to a Path object
MPIHandleVOID	if the object could not be created

See Also

[mpiPathDelete](#) | [mpiPathValidate](#)

mpiPathDelete

Declaration

```
long mpiPathDelete(MPIPath path);
```

Required Header: stdmpi.h

Description

mpiPathDelete deletes a Path object and invalidates its handle (*path*). PathDelete is the equivalent of a C++ destructor.

Return Values

[MPIMessageOK](#)

See Also

[mpiPathCreate](#) | [mpiPathValidate](#)

mpiPathValidate

Declaration

```
long mpiPathValidate(MPIPath path);
```

Required Header: stdmpi.h

Description

mpiPathValidate validates the Path object and its handle (*command*).

Return Values

[MPIMessageOK](#)

See Also

[mpiPathCreate](#) | [mpiPathDelete](#)

mpiPathParamsGet

Declaration

```
long mpiPathParamsGet(MPIPath path,
                      MPIPathParams *params,
                      void *external) ,
```

Required Header: stdmpi.h

Description

mpiPathParamsGet reads the parameters for a path object and writes them into the structure pointed to by **params**, and also writes it into the implementation-specific structure pointed to by **external** (if **external** is not NULL).

path	a handle to a Path object
*params	a pointer to a MPIPathParams structure
*external	a pointer to a void or NULL

Return Values

[MPIMessageOK](#)

See Also

[mpiPathParamsSet](#)

mpiPathParamsSet

Declaration

```
long mpiPathParamsSet(MPIPath path,
                     MPIPathParams *params,
                     void *external) ,
```

Required Header: stdmpi.h

Description

mpiPathParamsSet writes the parameters from the structure pointed to by **params** into the Path object. Also, it writes the implementation-specific structure pointed to by **external** (if **external** is not NULL) into the Path.

path	a handle to a Path object
*params	a pointer to a MPIPathParams structure
*external	a pointer to a void or NULL

Return Values

[MPIMessageOK](#)

See Also

[mpiPathParamsGet](#)

mpiPathAppend

Declaration

```
long mpiPathAppend(MPIPath         path,
```

```
                  MPIPathElement *element);
```

Required Header: stdmpi.h

Description

mpiPathAppend adds an array of path elements pointed to by **element** to the end of the **path** stored in the Path object.

Return Values

[MPIMessageOK](#)

See Also

[mpiPathCreate](#) | [mpiPathMotionParamsGenerate](#)

mpiPathMotionParamsGenerate

Declaration

```
long mpiPathMotionParamsGenerate(MPIPath path,  

                                MPIMotionParams *params);
```

Required Header: stdmpi.h

Description

mpiPathMotionParamsGenerate calculates a list of points from the path object and writes them into the motion params structure pointed to by params. After the motion params are generated, they can be passed to [mpiMotionStart\(...\)](#). Path generated params are supported with the following motion types:

- MPIMotionTypePT
- MPIMotionTypePTF
- MPIMotionTypePVT
- MPIMotionTypePVTF
- MPIMotionTypeSPLINE
- MPIMotionTypeBESSEL
- MPIMotionTypeBSPLINE
- MPIMotionTypeBSPLINE2

To create a path, use [mpiPathCreate\(...\)](#) to create a path object. Initialize the path parameters with [mpiPathParamsGet\(...\)](#) / [mpiPathParamsSet\(...\)](#). Then add path elements (line, arc, etc.) with [mpiPathAppend\(...\)](#). Before calling mpiPathMotionParamsGenerate(...) make sure to specify the [MPIMotionPoint{...}](#) values in the [MPIMotionParams](#) structure. It is very important to set point.final = TRUE or FALSE before calling mpiPathMotionParamsGenerate(...).

path	a handle to a Path object
*params	a pointer to a MPIMotionParams structure.

Return Values

[MPIMessageOK](#)

See Also

[mpiPathCreate](#) | [mpiPathParamsGet](#) | [mpiPathParamsSet](#) | [mpiPathAppend](#) | [mpiMotionStart](#)

MPIPathArc

Definition

```
typedef struct MPIPathArc {
    struct {
        double start;
        double included;
    } angle;
    double radius;
} MPIPathArc;
```

Description

MPIPathArc specifies the parameters for an arc path element. It supports 2 dimensional arcs only. All arcs start at the end position for the last path element added to the path or the present command position if the arc is the first element in the path.

start	This value defines the arc's starting angle. Units are in degrees.
included	This value defines the relative travel angle. Units are in degrees. Positive values specify counter-clockwise motion and negative values specify clockwise motion.
radius	This value defines the distance from the center to the arc edge. Units are in counts.

See Also

[MPIPathElement](#) | [MPIPathParams](#) | [MPIPathArcCenter](#)

MPIPathArcCenter

Definition

```
typedef struct MPIPathArcCenter {  
    MPIPathPoint    center;  
    double          angle;  
} MPIPathArcCenter;
```

Description

MPIPathArcCenter specifies the parameters for an arc path element. It supports 2 dimensional arcs only. All arcs start at the end position for the last path element added to the path or the present command position if the arc is the first element in the path.

center	This structure defines the coordinates for the center point of the arc. Please see MPIPathPoint data type documentation for more information.
angle	This value defines the relative travel angle. Units are in degrees. Positive values specify counter-clockwise motion and negative values specify clockwise motion.

See Also

[MPIPathElement](#) | [MPIPathParams](#) | [MPIPathArc](#)

MPIPathArcEndPoint

Definition

```
typedef struct MPIPathArcEndPoint {  
    MPIPathPoint     center;  
    MPIPathPoint     endPoint;  
    MPIPathDirection direction;  
} MPIPathArcEndPoint;
```

Description

MPIPathArcEndPoint specifies the parameters for an arc path element. It supports 2 dimensional arcs only. All arcs start at the end position for the last path element added to the path or the present command position if the arc is the first element in the path.

center	This structure defines the coordinates for the center point of the arc. Please see MPIPathPoint data type documentation for more information.
endPoint	This structure defines the coordinates for the final point of the arc. Please see MPIPathPoint data type documentation for more information.
direction	This value defines the travel direction, counter-clockwise or clockwise. Please see MPIPathDirection data type documentation for more information.

See Also

[MPIPathElement](#) | [MPIPathParams](#) | [MPIPathDirection](#)

MPIPathAttr

Definition

```
typedef enum {
    MPIPathElementAttrINVALID      = -1,
    MPIPathElementAttrRELATIVE     = MPIPathElementAttrLAST - 1,
    MPIPathElementAttrID           = MPIPathElementAttrLAST - 2,
    MPIPathElementAttrVELOCITY     = MPIPathElementAttrLAST - 3,
    MPIPathElementAttrACCEL        = MPIPathElementAttrLAST - 4,
    MPIPathElementAttrTIMESLICE    = MPIPathElementAttrLAST - 5,
    MPIPathElementAttrCOUNT        = MPIPathElementAttrLAST - MPIPathElementAttrFIRST,
} MPIPathAttr;
```

Description

In **MPIPathAttr**, the path attributes are used to generate the path attribute masks to enable features with `mpiPathAppend` (...). Please see [MPIPathElementAttrMask](#) data type for more information.

See Also

[mpiPathAppend](#)

MPIPathDirection

Definition

```
typedef enum {
    MPIPathDirectionCW = -1,
    MPIPathDirectionCCW = 1,
} MPIPathDirection;
```

Description

MPIPathDirectionCW	This value defines the clockwise direction.
---------------------------	---

MPIPathDirectionCCW	This value defines the counter-clockwise direction.
----------------------------	---

See Also

[MPIPathArcEndPoint](#)

MPIPathElement

Definition

```

typedef struct MPIPathElement {
    MPIPathElementType      type;
    long                  blending;
    union {
        MPIPathArc          arc;
        MPIPathArcCenter   arcCenter;
        MPIPathArcEndPoint arcEndPoint;
        MPIPathLine         line;
    } params;

    MPIPathElementAttributes attributes;
} MPIPathElement;

```

Description

type	This value defines the type of path element. Please see MPIPathElementType data type documentation for more information.
blending	This value determines whether the corners of the path are rounded or sharp. When set to TRUE, blending is enabled, causing rounded corners. When set to FALSE, blending is disabled, causing sharp corners.
arc	This structure defines the arc's start angle, included angle, and radius. This structure is used when the type is MPIPathElementTypeARC. Please see MPIPathArc data type documentation for more information.
arcCenter	This structure defines the arc's center and angle. This structure is used when the type is MPIPathElementTypeARC_CENTER. Please see MPIPathArcCenter data type documentation for more information.
arcEndPoint	This structure defines the arc's center, end point, and direction. This structure is used when the type is MPIPathElementTypeARC_END_POINT. Please see MPIPathArcEndPoint data type documentation for more information.
line	This structure defines the coordinates for a linear element. This structure is used when the type is MPIPathElementTypeLINE. Please see MPIPathLine data type documentation for more information.
attributes	This structure defines the attributes for a path element. Please see MPIPathElementAttributes data type documentation for more information.

See Also

[mpiPathAppend](#)

MPIPathElementAttributes

Definition

```
typedef struct MPIPathElementAttributes {
    long    id;           /* MPIPathAttrID */
    double  velocity;     /* MPIPathAttrVELOCITY */
    double  acceleration; /* MPIPathAttrACCELERATION */
    double  timeslice;    /* MPIPathAttrTIMESLICE */
} MPIPathElementAttributes;
```

Description

In **MPIPathElementAttributes**, the path attributes define the parameters to be used when specific features are enabled with the path element attribute masks. When using these attributes, be sure to enable the feature with the appropriate `MPIPathElementAttrMask{.}`.

id	This value defines an identification number to be stored in the path element. During path profile execution, at the start of each element the controller loads the id into the axis' ElementID field. The application can query the controller's axis memory to monitor the path element execution. The id is limited to 16-bit resolution by the controller firmware.
velocity	This value defines the velocity for the path element.
acceleration	This value defines the acceleration for the path element.
timeSlice	This value defines the time between interpolation points for the path element. The practical range for the time slice is from 10 msec (.01) to 100 msec (.1). Larger time slice values produce smoother (lower acceleration), less accurate paths. Smaller time slice values produce more accurate (both position and velocity) paths with higher peak accelerations.

See Also

[MPIPathElementAttrMask](#)

MPIPathElementAttrMask

Definition

```

typedef enum {
    MPIPathElementAttrMaskRELATIVE,
        = mpiPathElementAttrMaskBIT(MPIPathElementAttrRELATIVE),
    MPIPathElementAttrMaskID,
        = mpiPathElementAttrMaskBIT(MPIPathElementAttrID),
    MPIPathElementAttrMaskVELOCITY,
        = mpiPathElementAttrMaskBIT(MPIPathElementAttrVELOCITY),
    MPIPathElementAttrMaskACCEL,
        = mpiPathElementAttrMaskBIT
(MPIPathElementAttrACCEL),
    MPIPathElementAttrMaskTIMESLICE,
        = mpiPathElementAttrMaskBIT(MPIPathElementAttrTIMESLICE),

    MPIPathElementAttrMaskALL    = -1 << MPIPathElementAttrFIRST,
} MPIPathElementAttrMask;

```

Description

In **MPIPathElementAttrMask**, the path attribute masks are used to enable features with `mpiPathAppend(...)`. The masks are ORed with the `MPIPathElementType` to enable each feature.

MPIPathElementAttrMaskRELATIVE	This mask enables relative coordinates for path motion. This feature is not supported and is reserved for future use.
MPIPathElementAttrMaskID	This mask enables an identification tag to be stored in the path. Each element can have a unique identification. Please see MPIPathElementAttributes data type documentation for more information.
MPIPathElementAttrMaskVELOCITY	This mask enables a path velocity to be specified for each element. Please see MPIPathElementAttributes data type documentation for more information.
MPIPathElementAttrMaskACCEL	This mask enables a path acceleration to be specified for each element. Please see MPIPathElementAttributes data type documentation for more information.
MPIPathElementAttrMaskTIMESLICE	This mask enables a path time slice to be specified for each element. Please see MPIPathElementAttributes data type documentation for more information.

See Also

[MPIPathElementType](#) | [mpiPathAppend](#)

MPIPathElementType

Definition

```
typedef enum {
    MPIPathElementTypeINVALID,
    MPIPathElementTypeARC,           /* only 2D */
    MPIPathElementTypeARC_CENTER,    /* only 2D */
    MPIPathElementTypeARC_END_POINT, /* both 2D and 3D */
    MPIPathElementTypeHELIX,         /* not currently supported */
    MPIPathElementTypeIO,           /* not currently supported */
    MPIPathElementTypeLINE,         /* both 2D and 3D */

    MPIPathElementTypeMASK,
} MPIPathElementType;
```

Description

MPIPathElementTypeARC	This type generates an arc specified by the arc's start angle, included angle, and radius.
MPIPathElementTypeARC_CENTER	This type generates an arc specified by the arc's center and angle.
MPIPathElementTypeARC_END_POINT	This type generates an arc specified by the arc's center, end point, and direction.
MPIPathElementTypeLINE	This type generates a line specified by the position coordinates.

See Also

[MPIPathArc](#) | [MPIPathLine](#)

MPIPathLine

Definition

```
typedef struct MPIPathLine {  
    MPIPathPoint    point;  
} MPIPathLine;
```

Description

MPIPathLine specifies the parameters for a linear path element. It supports up to MPIPathPointDIMENSION_MAX dimensions. All lines start at the end position for the last path element added to the path or the present command position if the line is the first element in the path.

point

This structure defines the end point coordinates for the linear segment.

See Also

[MPIPathElement](#) | [MPIPathParams](#) | [MPIPathPointDIMENSION_MAX](#)

MPIPathMessage

Definition

```
typedef enum {
    MPIPathMessagePATH_INVALID,
    MPIPathMessageILLEGAL_DIMENSION,
    MPIPathMessageILLEGAL_ELEMENT,
    MPIPathMessageARC_ILLEGAL_DIMENSION,
    MPIPathMessageHELIX_ILLEGAL_DIMENSION,
    MPIPathMessageILLEGAL_RADIUS,
    MPIPathMessagePATH_TOO_LONG,
    MPIPathMessageILLEGAL_VELOCITY,
    MPIPathMessageILLEGAL_ACCELERATION,
    MPIPathMessageILLEGAL_TIMESLICE,
    MPIPathMessageINVALID_BLENDING,
} MPIPathMessage;
```

Description

MPIPathMessage is an enumeration of the Path error messages that can be returned by the MPI library.

MPIPathMessagePATH_INVALID

The path object is not valid. This message code is returned by a path method if the path object handle is not valid. This problem can be caused by a failed [mpiPathCreate\(...\)](#). To prevent this problem, check your path objects after creation by using [mpiPathValidate\(...\)](#).

MPIPathMessageILLEGAL_DIMENSION

The path dimensions are not valid. This message code is returned by [mpiPathParamsSet\(...\)](#) or [mpiPathMotionParamsGenerate\(...\)](#) if the path dimension is less than one or greater than or equal to MPIPathPointDIMENSION_MAX. Also, this message code is returned if specific path element types have dimension restrictions. For example, the ARC type is limited to 2 dimensions and the ARC_END_POINT type is limited to 3 dimensions. To correct this problem, select an appropriate dimension for the path element type.

MPIPathMessageILLEGAL_ELEMENT

The path element type is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the specified path element type is not a member of the [MPIPathElementType](#) enumeration.

MPIPathMessageARC_ILLEGAL_DIMENSION

The path element arc dimension is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the ARC or ARC_CENTER element is not 2 dimensions. To correct this problem, set the path dimension to 2.

MPIPathMessageHELIX_ILLEGAL_DIMENSION

Not supported.

MPIPathMessageILLEGAL_RADIUS

The path element arc radius is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the ARC element radius is less than or equal to zero. To correct this problem, set the arc radius to a value greater than zero.

MPIPathMessagePATH_TOO_LONG

The path length is not valid. This message code is returned by [mpiPathMotionParamsGenerate\(...\)](#) if the path length is greater than MAX_PATH_POINTS. To correct the problem, specify a path with fewer points than MAX_PATH_POINTS.

MPIPathMessageILLEGAL_VELOCITY

The path element velocity is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the specified velocity is less than or equal to zero. To correct this problem, set the element velocity to a value greater than zero.

MPIPathMessageILLEGAL_ACCELERATION

The path element velocity is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the specified velocity is less than or equal to zero. To correct this problem, set the element velocity to a value greater than zero.

MPIPathMessageILLEGAL_TIMESLICE

The path element time slice is not valid. This message code is returned by [mpiPathAppend\(...\)](#) if the specified time slice is less than or equal to zero. To correct this problem, set the element time slice to a value greater than zero.

MPIPathMessageINVALID_BLENDING

The path element blending is not valid. This message code is returned by [mpiPathMotionParamsGenerate\(...\)](#) if the element blending is set to TRUE and the motion type does not support blending. To correct this problem, either set the element blending to FALSE or select a different motion type.

See Also

MPIPathParams

Definition

```
typedef struct MPIPathParams {
    long           dimension;
    MPIPathPoint  start;
    double         velocity;
    double         acceleration;
    double         deceleration;
    MPIMotionType interpolation;
    double         timeSlice;
    double         conversion
    [MPIPathPointDIMENSION_MAX] [MPIPathPointDIMENSION_MAX];
} MPIPathParams;
```

Description

dimension	This value defines the number of axes to coordinate. Please see MPIPathPoint data type documentation for more information.
start	This structure defines the initial point for the path.
velocity	This value defines the speed along the path. The units are in counts per second.
acceleration	This value defines the rate of change of speed to reach the velocity along the path. The units are in counts per second * second.
deceleration	This value defines the rate of change of speed to reach zero velocity along the path. The units are in counts per second * second.
interpolation	This value specifies the motion algorithm to generate the path. Please see MPIMotionType data type documentation for more information.
timeSlice	This value specifies the amount of time between points. The units are in seconds. Smaller timeSlice values will improve the path accuracy, but increase the number of points to calculate and buffer.
conversion	<p>This value is an $N \times N$ matrix (where N is the number of dimensions in the path motion) that scales and rotates the axes used in the path motion. This is useful when using two axes with different resolutions for each axis.</p> <p>For two axes with different resolution: Set conversion[0][0] to (desired x resolution / actual x resolution) Set conversion [1][1] to (desired y resolution / actual y resolution) Set conversion[0][1] and conversion[1][0] = 0</p> <p>For a coordinate rotation, where alpha is the rotation of the coordinate system: Set conversion[0][0] and conversion [1][1] = cos(alpha) Set conversion[0][1] = sin(alpha)</p>

Set conversion[1][0] = -sin(alpha)

See Also

[mpiPathParamsGet](#) | [mpiPathParmsSet](#) | [mpiPathMotionParamsGenerate](#) | [MPIPathPointDIMENSION_MAX](#)

MPIPathPoint

Definition

```
typedef struct MPIPathPoint {  
    double  position[MPIPathPointDIMENSION_MAX];  
} MPIPathPoint;
```

Description

position

This array defines the axis command positions for a path point. There must be one position value for each dimension.

See Also

[MPIPathParams](#) | [mpiPathParamsGet](#) | [mpiPathParmsSet](#) | [mpiPathPointDIMENSION_MAX](#)

mpiPathElementTYPE

Declaration

```
#define mpiPathElementTYPE(type) ((type) & MPIPathElementTypeMASK)
```

Required Header: stdmpi.h

Description

mpiPathElementTYPE is a macro that masks off all other bits in type, leaving the path element type.

See Also

[MPIPathElementType](#)

mpiPathElementAttrMaskBIT

Declaration

```
#define mpiPathElementAttrMaskBIT(attr) (0x1 << (attr))
```

Required Header: stdmpi.h

Description

mpiPathElementAttrMaskBIT is a macro that converts the path element attribute into the path element attribute mask.

See Also

[MPIPathElementAttrs](#) | [MPIPathElementAttrMask](#)

mpiPathElementATTR

Declaration

```
#define mpiPathElementATTR(type,attr)
    ((type) |= mpiPathElementAttrMaskBIT\(attr\))
```

Required Header: stdmpi.h

Description

mpiPathElementATTR is a macro that turns on the specified path element attribute mask bits in the path element type.

See Also

[MPIPathAttr](#) | [MPIPathElementAttrMask](#)

MPIPathPointDIMENSION_MAX

Definition

```
#define MPIPathPointDIMENSION_MAX ( 16 )
```

Description

MPIPathPointDIMENSION_MAX defines the maximum dimensions for path objects.

See Also

[MPIPathParams](#) | [mpiPathParamsGet](#) | [mpiPathParmsSet](#) | [mpiPathPointDIMENSION_MAX](#)

MPIPathPointPOINTS_MAX

Definition

```
#define MPIPathPointPOINTS_MAX ( 5000 )
```

Description

MPIPathPointPOINTS_MAX defines the maximum number of points for a path.

See Also

[MPIPathParams](#) | [mpiPathMotionParamsGenerate](#)